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| Team Meeting | 3/2/203:30pmJD 2016 |

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| Meeting called by: | Class Scheduled | Type of meeting: | Partial Sprint Presentation |
| Facilitator: | Gigi | Note taker: | Daniel |
| Timekeeper: | Daniel |  |  |

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| Attendees: | Gigi, Brandon, Gage, Daniel |
| Please read: | n/a |
| Please bring: | n/a |

# Minutes

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| Agenda item: | Gigi Sprint Presentation | Presenter: | Gigi |

#### Discussion:

* Totally Aquatic ROV. Cannot be run outside of water.
* Demo tested for speed. Lasted about 5-10 seconds
* Able to get 3D coordinates
* Going to test; what told to do and what actually happened
* Use python algorithm

#### Conclusions:

Testing was successful, though short. More extensive testing will be made created in the future.

| Action items | Person responsible | Deadline |
| --- | --- | --- |
| * Plot a graph of movement tracking | Gigi | Undetermined; Before final testing |
| * Future will test expected pathing results/coordinates with actual, physical results | Gigi | Undetermined |
| * Use python algorithm in physical pathing | Daniel and Gigi | Undetermined; Before next extensive testing |

# Other Information

#### Observers:

Professor Doussette, Team Members

#### Resources:

iPhone to show video of testing. Unable to use external resource due to security issues associated with intellectual property.

#### Special notes:

n/a